Control, Acquisition, and Post-Processing of LiDAR Data for Corridor Work -Utility and Transportation-

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# Control

- What is required by the scope of work?
- 1. Specifications of required accuracy (H & V)
- 2. What datum is required for final delivery
- 3. Who is to provide the control and their experience performing the task

# Specifications of required accuracy

- Accuracy and point density determines the system to be utilized in most cases (terrestrial, mobile, airborne).
- Most requirements are specified as points per square meter (ppsm) and a value horizontally and vertically.
- As few as 2-3 ppsm for flood studies to 50+ ppsm for power line location for definition of objects
- Horizontal accuracy rarely defined in RFP. Easier to verify the higher the point density. Horizontal accuracy is usually a component of vertical accuracy requirement.
- Vertical accuracy may be specified as an absolute value (1.5cm to 1m) for airborne systems.
- Accuracy may also be required to meet a set of standards such as USGS, ASPRS, etc. Especially true when providing data to federal and state agencies

## Specifications (cont.)

- Control for the purpose of <u>absolute calibration</u> of LiDAR data should be located on hard level surfaces.
- If used for evaluating the horizontal accuracy then distinct objects such as painted aerial targets or photo identifiable objects should be located. As most of our LiDAR projects have an orthomosaic component the control serves a dual purpose.
- Control for <u>validation</u> of the final LiDAR dataset will normally be collected on different surfaces (pavement, bare ground, grass, kudzu, open woods, etc.).

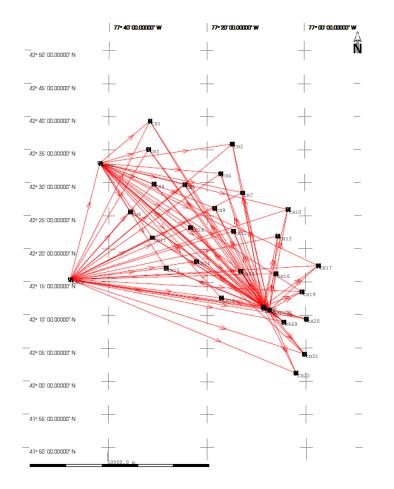
# Datum required for delivery

- 1. As a contractor we have to assume the client is always right! Whatever datum the client requests the contractor is obligated to provide. We deal with this on a daily basis. If you think NAD27 and NGVD29 are dead, think again.
- 2. Most vertical control is required to be in NAVD88 in either meters or feet (US or International). But there are areas where this is not the case.
- 3. The higher the vertical accuracy required, the more control required, and the method to produce the control must exceed the vertical accuracy (if 2cm is required, control can't be 5cm). Roadways usually require spirit leveling while power line control usually can be acquired with GPS in various forms (RTK (base and network), static, OPUS, OPUS-RS).
- 4. Horizontal datum is across the spectrum from NAD27 to NAD83(XX) to UTM zones to project coordinates.

# **Providing Control**

- Know your limitations and work within them. If you have never provided control to 1cm accuracy maybe this one project is not for you.
- 2. Know the limitations of your personnel and equipment. Even if the control is to the CM if the panel is painted 0.5m off it will make the data appear off.
- 3. Know the requirements of reporting (they can be more demanding than acquiring the control).

## CORS, BM's, Will it fit ?



- If using CORS are they Height Modernization stations. What is the spacing?
- If using BM's are they on the datum required (most USGS and TVA BM's are on NGVD29 for instance).
- If relative to tidal datum (MLLW = 0) BM's associated with tide gages are referenced to the tidal epoch, some may have NGVD29 elevations, and some may have NAVD88 elevations.



## Platforms Available for LiDAR Missions





Bell 407 N196TA



#### Bell LongRanger 206LIII N194TA



Bell JetRanger 206BIII N192TA



LiDAR System



Cessna 206 – N193TA

TUCK MAPPING SOLUTIONS, INC.

## Tuck Mapping Solutions, Inc. LiDAR Platform





TUCK MAPPING SOLUTIONS, INC.



Inertial Navigation System (INS), control and data recording unit

**GPS** receiver

Laser unit, — Deflection unit, and Ranging unit (exterior mounted)

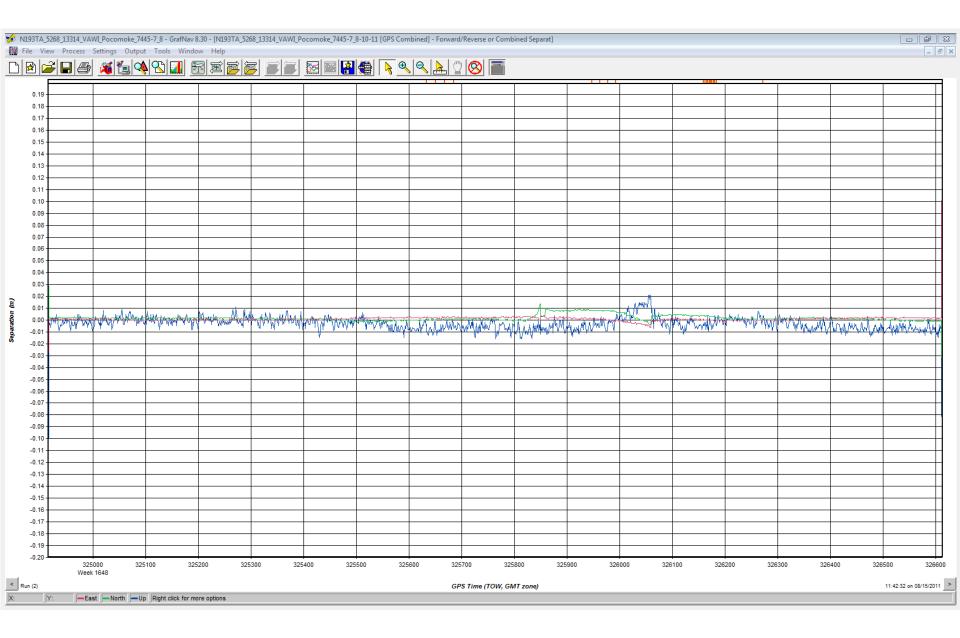


# Acquiring Airborne LiDAR Data

- As the trajectory is the single component driving the accuracy of the LiDAR data, mission planning is critical.
- The better the satellite geometry the better the chance of acquiring suitable data. There are sometimes when it is counterproductive to fly (yes really!).
- With the upcoming geomagnetic storms due to Solar Cycle 24, even more emphasis on mission planning will be required.
- Weather, restricted airspace (you want to do what where?), aircraft support staff required and available, etc. affect flight schedules.
- We have utilized both ground stations and CORS on projects in combination. The ground control must be relative to whatever we use.
- We usually initialize on the ground but regularly do so on the fly as well. Both require 10 minutes of data but on the fly requires a fairly straight line when approaching and leaving the base station.
- Communication between aircraft and ground crew is desirable especially where cell phone coverage is minimal.
- Current flight plans and suitable data storage capacity are part of the preflight review. Our LiDAR systems produce from 250 gigabytes to 1 terabyte of data during a three hour mission.

# Post-processing of LiDAR Data

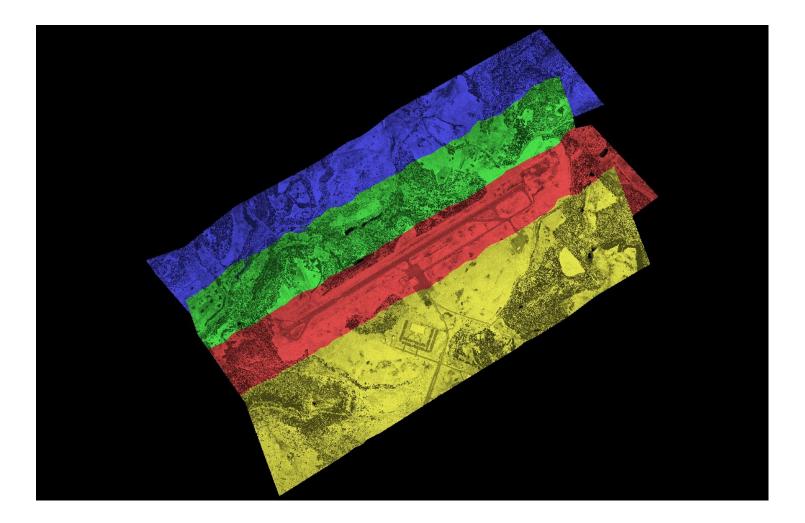
- Aircraft data is downloaded and backed up after each flight.
- Flight crew has the capability to review the data set for coverage and determine if any gaps exist due to terrain primarily.
- The base station data is downloaded and backed up by day regardless of the number of flights.
- The aircraft trajectory is computed by combining base station and aircraft data. One second epoch data is required on the base station. The aircraft is capable of collecting data at 0.2 second intervals.
- The trajectory should look like the following:



## Post-processing (cont.)

- Trajectory fixes the position and elevation of the GPS antenna. Offsets to the IMU, scanner, and cameras are surveyed. Software georeferences data to compute position and elevation of LiDAR returns.
- The software defaults to WGS84 latitude and longitude and ellipsoid heights in GEOID09.
- Software analyzes data to locate overlapping datasets (planar surfaces) and computes the angular misalignment between the IMU and the LiDAR scanner to align the data. This is where you find out how good your equipment and calibration is. Note that control is not being utilized during this process. It may take more than 8 hours for the initial calibration results (waveform processed) from a single 3 hour lift and multiple runs may be necessary but requiring less time.

### Example of flight lines and sidelap used to calibrate datasets



## **Calibration Report**

RiPROCESS Scan Data Adjustm	ent Protocol
Project:	8247-Detroit Light Rail Line LiDAR 06-06-11
Protocol date:	2011-07-14 14:36
Operator:	MJD
Comments:	
Program version:	RiPROCESS v1.4.8 (2010-11-15)
Computer:	TUCK144
Physical units:	ft, deg

#### **Observation parameters**

Calculation parameters	
Calculation mode:	Adjustment
Calculation time:	45 mins, 24 secs, 901 msecs
Calculation mode:	Robust
Tolerance:	0.00000
Search corresp. planes:	True
Search radius [ft]:	3.281
Angular tolerance [deg]:	5.000
Max. normal dist. [ft]:	3.281
Observations active:	True
Observations count:	4841

Calculation results	
Number of free parameters:	18
Number of observations:	4841
Error (Std. deviation) [ft]:	0.0580

Name	Roll	Pitch	Yaw	East	North	Height	Time
110606_100613	0.000	-0.014	0.004	0.401	-0.446	-0.074	0.000
- Confidence	0.000021	0.000143	0.000129	0.000000	0.000000	0.000000	0.000000
110606_102715	-0.002	-0.013	-0.012	0.360	-0.421	-0.016	0.000
- Confidence	0.000057	0.000146	0.000227	0.000000	0.000000	0.000000	0.000000
110606_103755	0.000	-0.002	-0.006	-0.075	0.358	0.003	0.000
- Confidence	0.000174	0.000136	0.000513	0.000000	0.000000	0.000000	0.000000
110606_105327	-0.001	-0.003	-0.005	-0.069	0.397	0.016	0.000
- Confidence	0.000208	0.000170	0.000465	0.000000	0.000000	0.000000	0.000000
110606_105812	0.002	-0.007	0.008	-0.023	0.178	0.031	0.000
- Confidence	0.000103	0.000205	0.000414	0.000000	0.000000	0.000000	0.000000
110606_110053	0.002	-0.008	0.000	0.080	0.021	0.027	0.000
- Confidence	0.000128	0.000213	0.000202	0.000000	0.000000	0.000000	0.000000

Tilt mounts			
Name	Roll	Pitch	Yaw

#### Laser devices

Name	Roll	Pitch	Yaw	Х	Y	Z	Range Shift
Scanner 1 (Q680i, 9998212)	0.00047	0.45160	-0.41530	0.000	0.000	0.000	0.0000
- Confidence	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.0000

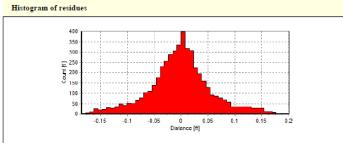
#### Navigation devices

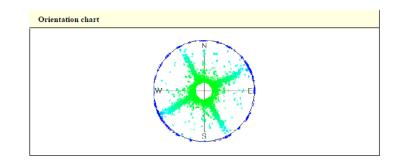
Name	Roll	Pitch	Yaw	East	North	Height	Time
INS-GPS 1 (INS Type 01, 9998212)	0.000	0.000	0.000	0.000	0.000	0.000	15.0000
- Confidence	0.000000	0.000000	0.000000	0.000000	0.000000	0.000000	0.0000000

Best 15 obse	ervations			
#	Object 1	Object 2	Deviation	Description
1	110606_102715	110606_110053	0.000	
2	110606_100613	110606_105812	0.000	
3	110606_105812	110606_110053	0.000	
4	110606_100613	110606_102715	0.000	
5	110606_103755	110606_105327	0.000	
6	110606_103755	110606_105327	0.000	
7	110606_100613	110606_105812	0.000	
8	110606_100613	110606_102715	0.000	
9	110606_102715	110606_110053	0.000	
10	110606_100613	110606_102715	0.000	
11	110606_100613	110606_102715	0.000	
12	110606_100613	110606_102715	0.000	
13	110606_103755	110606_105327	0.000	
14	110606_103755	110606_105327	0.000	
15	110606 100613	110606 102715	0.000	

## **Calibration Report**

#	Object 1	Object 2	Deviation	Description
1	110606_103755	110606_105327	0.197	
2	110606_105812	110606_110053	0.181	
3	110606_100613	110606_102715	-0.181	
4	110606_100613	110606_102715	-0.180	
5	110606_105812	110606_110053	-0.177	
6	110606_103755	110606_105327	-0.177	
7	110606_103755	110606_105327	0.176	
8	110606_105812	110606_110053	0.176	
9	110606_100613	110606_102715	-0.175	
10	110606_103755	110606_105327	-0.174	
11	110606_105812	110606_110053	0.173	
12	110606_105812	110606_110053	-0.173	
13	110606_100613	110606_102715	0.172	
14	110606_103755	110606_105327	-0.171	
15	110606_100613	110606_102715	0.171	
Best 6 scans				
Name			Objects	Std. dev
110606_102715			3789	0.054
110606_100613			3790	0.055
110606_105812			679	0.067
110606_110053			653	0.067
110606_103755			386	0.073
110606_105327			385	0.073
Worst 6 scans				
Name			Objects	Std. dev
110606_105327			385	0.073
110606_103755			386	0.073
110606_110053			653	0.067
110606_105812			679	0.067
110606_100613			3790	0.055
110606 102715			3789	0.054





Verification of post-processed data

- Control data is compared to a LiDAR derived surface.
- Most of the datasets we have collected check to the control ≤3 cm due to multiple factors as noted. Control and base station data are the same and are of excellent quality. Flight planning is critical. Calibration of the system is survey quality.
- Data can be raised or lowered to a base to match the control if necessary. Our systems produce data that is normally 1.5-3cm high compared to control. We have multiple systems and all are within the same tolerance.

### LiDAR absolute control check

	oit\Ground Contro			Lacon 7	0.7	CP603	13458184.558	347239.821	640.498	outside
nber	Easting	Northing	Known Z	Laser Z	Dz	CP604	13458745.359	347541.248	639.446	outside
100	13458651.330	347311.094	639.906	outside	*	CP605	13459267.406	347691.482	637.881	outside
L01	13459130.506	346188.028	639.943	outside	*	CP606	13458897.224	346401.698	638.679	outside
	13459382.577	345478.059	640.129	640.120	-0.009	CP607	13459235.496	346516.297	636.691	outside
L02	13459913.648	344630.316	640.527	640.490	-0.037	CP608	13459548.519	347281.353	636.518	outside
103	13461064.312	342254.932	638.906		+0.024	CP609	13459088.679	345448.837	637.487	outside
104				638.930		CP610	13459750.602	345760.517	639.816	outside
105	13461481.213	341616.393	640.270	640.220	-0.050	CP611	13460226.679	343854.685	638.706	638.620
106	13462411.613	339895.061	640.547	640.560	+0.013	CP612	13460660.088	344059.337	637.442	outside
107	13462932.921	339073.444	640.127	640.240	+0.113	CP613	13460634.922	342525.274	638.915	outside
108	13463142.538	338481.399	638.531	638.620	+0.089	CP614	13461068.613	342636.707	639.204	639.170
109	13463457.271	337856.158	637.868	637.870	+0.002	CP615	13461808.469	340807.645	640.902	640.830
110	13464031.899	336974.577	637.520	outside	*	CP616	13462161.214	341053.437	639.534	outside
111	13464291.833	336261.131	636.056	636.120	+0.064	CP617	13462486.909	339528.747	640.891	640.840
112	13464717.177	335633.404	635.731	635.710	-0.021	CP618	13462874.372	339731.326	638.572	outside
L13	13464804.427	335252.928	635.273	635.200	-0.073	CP619		338115.887		
L14	13465492.623	333870.074	634.847	634.810	-0.037		13463093.795		639.177	639.150
L15	13466027.982	333105.810	635.468	635.510	+0.042	CP620	13463527.712	338309.733	636.093	outside
L16	13466132.792	332701.710	636.198	636.150	-0.048	CP621	13463723.487	337110.638	639.063	639.070
L17	13466431.896	332331.309	637.856	637.890	+0.034	CP622	13464218.796	337251.169	637.548	outside
118	13466544.461	331877.723	639.101	639.100	-0.001	CP623	13464346.073	335784.451	635.897	outside
119	13466883.637	331257.210	639.821	639.800	-0.021	CP624	13464713.043	336071.450	635.053	outside
120	13467303.495	330649.365	641.352	641.430	+0.078	CP625	13464708.623	334663.785	636.097	outside
121	13467438.053	330164.476	641.872	641.870	-0.002	CP626	13465320.427	334912.739	634.840	outside
122	13468251.532	328813.606	635.804	635.830	+0.026	CP627	13466103.811	334842.487	635.807	outside
L23	13468440.493	328230.732	633.923	634.060	+0.137	CP628	13466196.591	335396.606	634.146	outside
124	13468853.173	327650.565	633.509	633,500	-0.009	CP629	13466586.368	334626.488	635.873	outside
L25	13469332.240	326745.984	634.796	634.870	+0.074	CP630	13467432.837	336051.692	634.242	outside
126	13469887.241	325641.134	634.427	634.470	+0.043	CP631	13467674.737	335605.678	634.627	outside
127	13470113.846	325017.423	632.068	632.120	+0.052		13467913.907			
128	13470426.816	324624.855	632.240	632.340	+0.100	CP632		335241.674	635.282	outside
29	13470587.380	324104.788	631.080	631.070	-0.010	CP633	13465324.492	333592.580	638.815	outside
130	13471416.189	322702.189	631.801	631.860	+0.059	CP634	13465959.161	333929.309	637.952	outside
131	13471543.481	322269.798	630.784	slope	*	CP635	13466073.918	332294.413	636.400	outside
132	13471884.910	321785.046	630.630	630.690	+0.060	CP636	13466528.250	332497.311	637.463	outside
		320806.146	630.630			CP637	13466770.644 13467232.637	331016.801 331239.446	639.849 642.016	outside
133	13472397.867			630.630	+0.030	CP638	13467232.637	331239.446	642.016	outside
134	13472555.399	320309.166	630.660	630.690	+0.030	CP639	13467475.432	329734.914	641.329	outside
135	13472887.719	319859.605	630.956	630.990	+0.034	CP640	13467740.275	329824.812	639.694	639.670
136	13473124.703	319162.170	630.781	630.830	+0.049	CP641	13468071.073	328379.887	635.562	outside
137	13473447.069	318754.301	630.491	630.530	+0.039	CP642	13468549.035	328651.445	635.256	outside
138	13473889.942	317900.716	632.039	632.050	+0.011	CP643	13468992.140	327194.157	634.584	634.570
139	13474158.158	317214.995	631.418	631.450	+0.032	CP644	13469224.206	327384.974	634.004	outside
140	13474736.318	316055.008	631.398	631.410	+0.012	CP645	13469664.172	325899.394	634.101	634.050
141	13475327.600	314901.133	628.179	628.210	+0.031	CP646	13469920.527	326037.736		
142	13475743.498	314287.568	626.475	626.500	+0.025	CP646			633.731	outside
143	13476086.484	313486.380	623.597	623.640	+0.043	CP647	13470279.289	324592.790	632.111	632.090
144	13476380.321	313173.250	623.130	623.190	+0.060	CP648	13470698.736	324826.192	630.920	outside
145	13476465.456	312747.393	621.834	621.850	+0.016	CP649	13471008.925	323301.864	630.215	630.170
146	13476977.516	312003.637	619.082	619.130	+0.048	CP650	13471293.038	323437.594	631.027	outside
147	13477119.785	311492.086	617.851	617.870	+0.019	CP651	13471478.182	321886.071	630.743	outside
48	13477546.923	310922.217	615.943	616.020	+0.077	CP652	13471890.936	322125.374	630.709	outside
49	13477759.815	310240.629	615.386	615.420	+0.034	CP653	13472132.399	320633.770	631.131	outside
50	13478503.110	309043.790	609.362	609.430	+0.068	CP654	13472647.272	320832.658	630.992	outside
51	13478811.909	308463.173	603.460	603.480	+0.020	CP655	13472887.551	319302.175	630.160	outside
52	13479008.563	308116.277	603.751	603.750	-0.001	CP656	13473307.999	319535.314	629.821	outside
153	13479201.934	307488.138	600.821	600.790	-0.031	CP657	13473669.329	318078.221	631.906	631.910
154	13479451.906	307067.097	597.017	596.990	-0.027	CP658			631.419	
155	13479638.317	306758.616	598.634	598.620	-0.014		13473958.108	318132.209		outside
156	13479888.422	306347.237	600.742	600.710	-0.032	CP659	13474194.761	316668.559	631.863	outside
157	13480117.980	305942.767	599.486	599.450	-0.032	CP660	13474473.701	316828.773	631.282	631.280
158	13480223.277	305670.480	601.382	601.330	-0.052	CP661	13474861.694	315382.455	631.613	outside
158	13480223.277	305090.272	598.614	outside	-0.052	CP662	13475122.372	315559.656	630.585	630.560
					*	CP663	13475496.882	314295.137	627.389	outside
L60	13480969.078	304749.401	600.138	outside	*	CP664	13475932.539	314510.570	626.864	outside
161	13480280.273	304340.297	602.544	outside		CP665	13476235.355	312839.440	624.401	outside
162	13479434.761	305196.688	607.806	607.810	+0.004	CP666	13476673.514	313109.208	625.459	outside
163	13479183.791	305476.521	604.823	604.790	-0.033	CP667	13476933.314	311489.109	618,493	outside
164	13479093.999	305812.165	599.335	599.360	+0.025	CP668	13477289.579	311753.195	619.757	outside
165	13478999.479	306532.438	598.004	outside	*	CP669	13477520.839	310213.800	617.454	outside
601	13457958.695	348156.081	642.133	outside	*		12477006 135			
602	13458270.266	348357.796	640.133	outside	*	CP670	13477996.125	310452.561	617.743	outside
		F	Page 1			CP671	13478301.665 13478605.159	308854.112 309147.191	609.232 610.211	outside
						CP672				

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### LiDAR absolute control check (cont.)

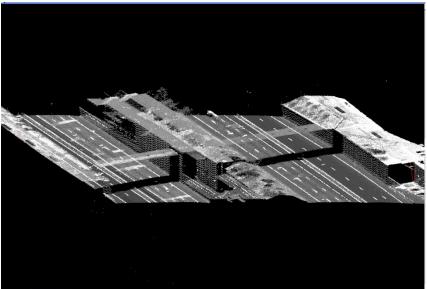
CP674	13479455.816	307663.692	600.092	outside	*
CP675	13478526.702	306007.606	597.072	outside	*
CP676	13479059.496	306319.656	597.991	outside	*
CP677	13479583.049	306242.608	599.901	outside	*
CP678 CP679	13480286.851 13479258.825	306530.603 305086.891	603.122 607.905	outside outside	*
CP680	13480584.261	305884.215	598.262	outside	*
CP681	13479878.161	304986.916	594.891	594.970	+0.079
CP682	13480600.465	305368.847	594.683	594.660	-0.023
CP683	13479653.424	304629.954	590.444	590.420	-0.024
CP684	13480405.076	304935.737	594.861	outside	*
CP685	13479977.318	304156.405	601.540	outside	*
CP686	13481142.776	304859.227	600.803	outside	*
CP901 CP901A	13458922.671 13458828.152	346756.637 346729.232	637.561 637.435	outside	*
CP901B	13458762.807	346654.109	638.103	outside	*
CP902	13460708.880	343119.993	639.187	639.120	-0.067
CP902A	13460636.957	343067.901	639.624	639.540	-0.084
CP902B	13460810.524	343150.175	640.270	640.220	-0.050
CP903	13462109.860	340447.210	641.857	641.800	-0.057
CP903A	13462045.698	340351.721	641.863	641.830	-0.033
CP903B CP904	13462200.230 13463714.371	340473.725 337444.592	641.516 637.555	641.440 637.520	-0.076
CP904A	13463656.851	337373.181	637.878	637.840	-0.038
CP904B	13463825.706	337428.689	638.117	638.060	-0.057
CP905	13465192.669	334367.299	632.757	632.660	-0.097
CP905A	13465065.841	334302.600	634.449	outside	*
CP905B	13465301.727	334491.009	634.081	634.040	-0.041
CP906	13465909.198	334438.170	636.029	outside	*
CP906A CP906B	13465809.184 13466064.313	335000.619 334302.053	636.193 636.884	outside	*
CP907	13466841.932	335693.306	634.355	outside	*
CP907A	13466769.910	335768.150	634.776	outside	*
CP907B	13467014.841	334857.422	635.742	outside	*
CP908	13466723.970	331643.618	639.551	639.470	-0.081
CP908A	13466765.740	331668.105	639.076	639.060	-0.016
CP908B	13466670.063	331615.438	639.048	639.030	-0.018
CP909 CP909A	13468003.994 13467944.069	329271.527 329210.047	635.929 636.277	635.920	-0.009
CP909B	13468219.289	329341.441	635.158	outside	-0.047
CP910	13469513.212	326356.405	635.093	635.150	+0.057
CP910A	13469446.110	326320.553	635.145	635.140	-0.005
CP910B	13469855.382	326629.863	634.977	outside	*
CP911	13470726.754	323786.909	630.527	outside	*
CP911A	13470580.349	323663.339	629.833	outside	*
CP911B CP912	13470844.914 13472170.696	323793.814 321252.093	630.516 630.194	outside 630.210	+0.016
CP912A	13472090.587	321185.326	630.214	630.220	+0.006
CP912B	13472332.707	321298.807	629.613	outside	*
CP913	13473450.632	318487.847	631.441	631.420	-0.021
CP913A	13473285.723	318401.809	630.550	outside	*
CP913B	13473624.349	318510.235	631.071	631.050	-0.021
CP914 CP914A	13475442.264 13474995.007	314951.501 314743.961	628.608	628.700 outside	+0.092
CP914B	13475745.313	315101.220	626.949 630.724	outside	*
CP915	13476698.801	312297.711	620.615	620.610	-0.005
CP915A	13476516.238	312192.946	621.227	outside	*
CP915B	13477009.044	312461.364	622.487	outside	*
CP916	13478117.405	309685.440	612.892	612.900	+0.008
CP916A	13478066.272	309658.692	612.328	612.310	-0.018
CP916B	13478154.610	309733.858	612.754	612.830	+0.076
CP917 CP917A	13479737.176 13479481.797	306749.894 306659.176	598.994 599.803	599.020 outside	+0.026
CP917A CP917B	13479943.799	306880.520	600.471	outside	*
CP918	13479143.865	305605.401	602.908	602.900	-0.008
CP918A	13479469.541	305748.866	602.746	outside	*
CP918B	13479714.948	305163.749	604.607	outside	*
CP919	13480183.212	305907.585	599.320	599.260	-0.060
CP919A	13479745.117	305931.305	600.831	outside	*
CP919B CP920	13480378.050 13480115.480	306065.298 305139.020	600.472 592.691	600.540 592.640	+0.068
Cr 320	13400113.480			332.040	0.051
		8	Page 3		

CP920A	13479907.558	305011.785	594.699	594.730	+0.031
CP920B	13480233.869	305226.694	592.652	592,610	-0.042
CP921	13479968.799	304679.559	593.993	594.020	+0.027
CP921A	13479710.981	304534.246	590.034	590.030	-0.004
CP921B	13480076.131	304752.760	594.668	removed	*
CP922	13480798.764	305004.043	598.524	outside	*
CP922A	13480632.889	304773.144	601.473	outside	*
CP922B	13480998.489	304993.115	600.891	outside	*
CP9000	13467103.860	324196.447	637.425	outside	*
CP9001	13480495.216	303782.978	580.347	outside	*
CP9002	13473011.636	313820.195	625.083	outside	*
CP9003	13477574.513	318085.480	634.934	outside	*
CP9004	13467826.800	337231.079	633.582	outside	*
CP9005	13459409.494	336803.371	649.495	outside	*
CP63684	13456711.822	347445.536	647.810	outside	*
CP63685	13463813.228	347792.004	634.910	outside	*
CP82663	13470281.582	326903.027	633.276	outside	*
CPSEMEN	13486012.973	306344.412	580.020	outside	*
Average dz	+0.001'				
Minimum dz	-0.097				
Maximum dz	+0.137				
Average magnitu					
Root mean squar					
Std deviation	0.048				

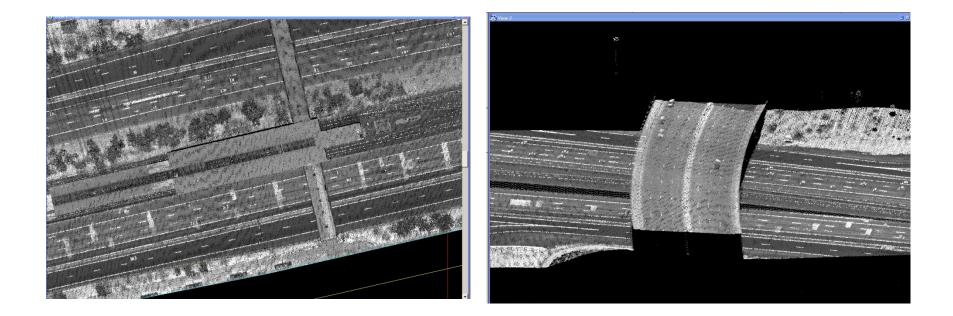
Page 4

## Transportation





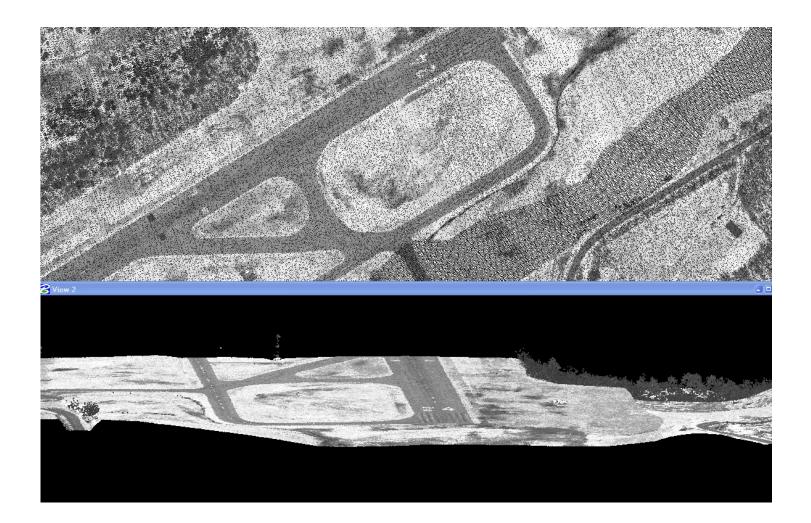
## Transportation



## Transportation

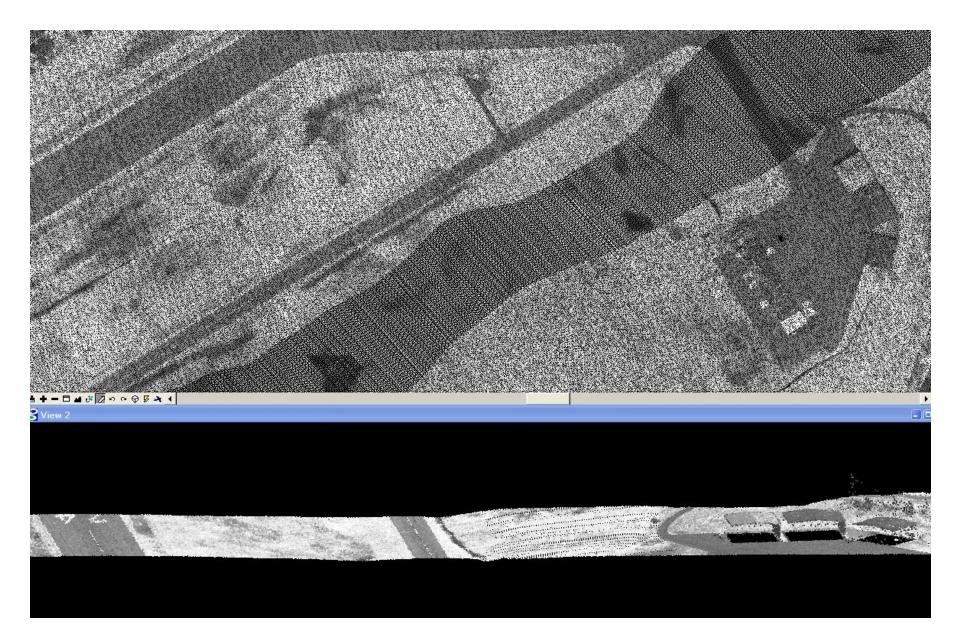


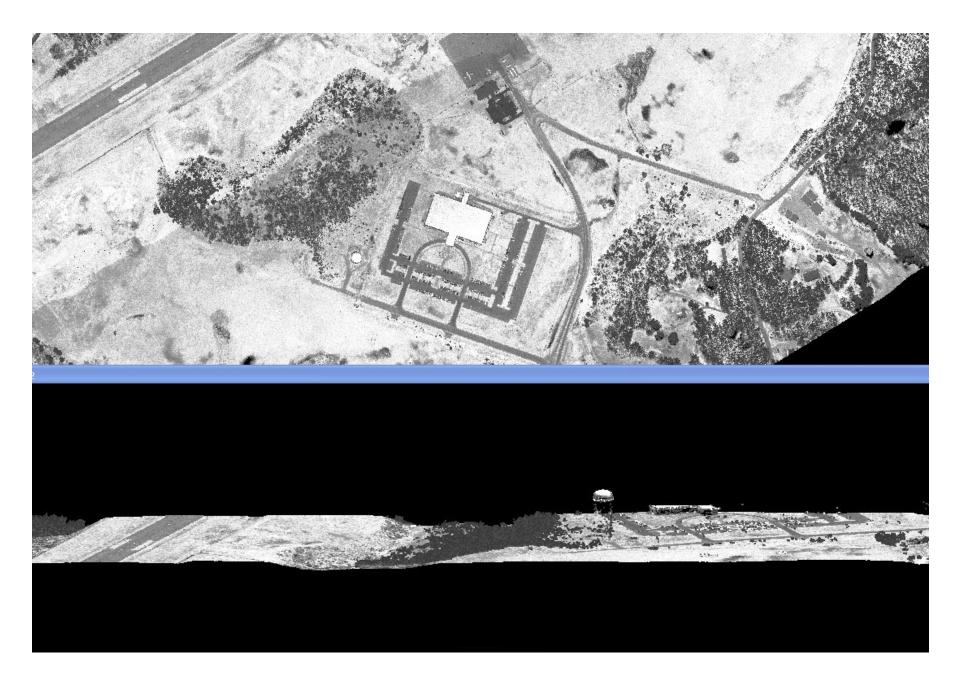
### Airport obstruction surveys





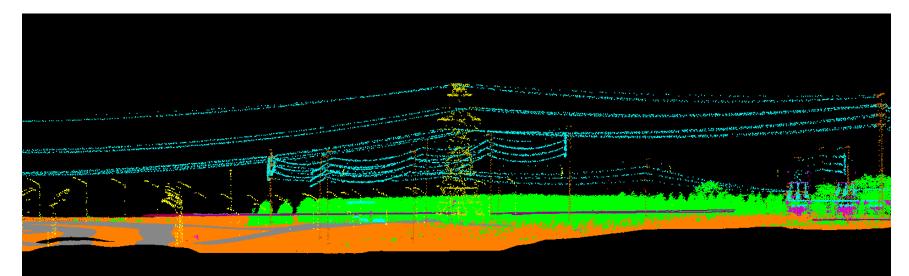


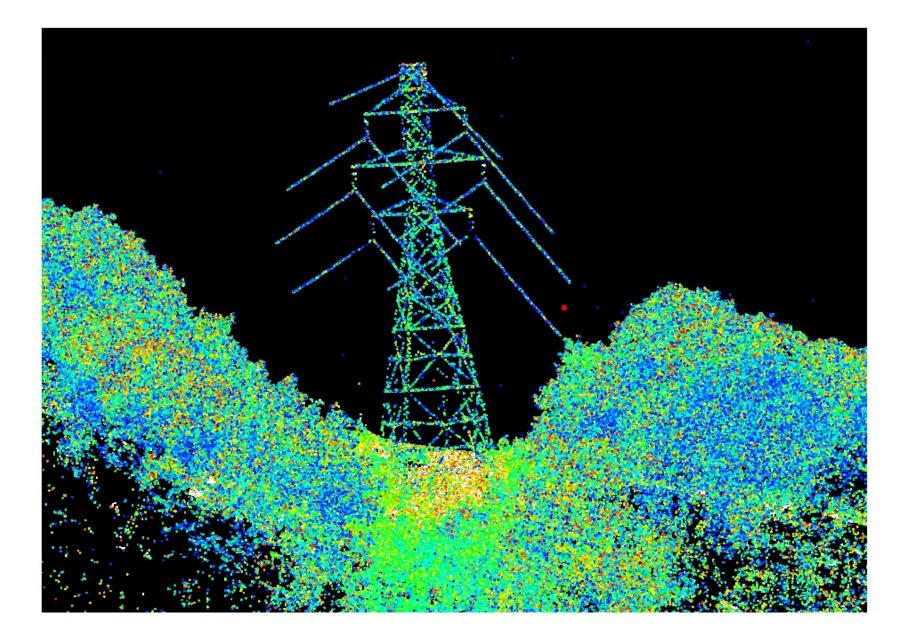




### Utilities

Progress.dgn (3D - VB DGN) - MicroStation VB 2004 Edition			
Bie Edit Element Settings Tools (Elities Workspace Applications Window Help		Main	
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### Study of Oxbow Area, White River, AR

